

# Powerful actuation of magnetized microtools by focused magnetic field for particle sorting in a chip

Yamanishi Y., Sakuma S., Onda K., Arai F.

Japan Science and Technology Agency (JST), Department of Mechanical Science and Engineering, Nagoya University, Furo-cho, Chikusa-ku, Nagoya, 464-8603 Aichi-ken, Japan; Department of Bioengineering and Robotics, Tohoku University, 6-6-01, Aramaki-Aza-Aoba, Aoba-ku, Sendai, Miyagi-ken 980-8579, Japan; Department of Mechanical Science and Engineering, Nagoya University, Furo-cho, Chikusa-ku, Nagoya, 464-8603 Aichi-ken, Japan

**Abstract:** This paper describes a novel powerful noncontact actuation of a magnetically driven microtool (MMT), achieved by magnetization of the MMT and focusing of the magnetic field in a microfluidic chip for particle sorting. The following are the highlights of this study: (1) an MMT was successfully fabricated from a mixture of neodymium powder and polydimethylsiloxane; the MMT was magnetized such that it acted as an elastic micromagnet with a magnetic flux density that increased by about 100 times after magnetization, and (2) a pair of sharp magnetic needles was fabricated adjacent to a microchannel in a chip by electroplating, in order to focus the magnetic flux density generated by the electromagnetic coils below the biochip; these needles contribute to miniaturization of an actuation module that would enable the integration of multiple functions in the limited area of a chip. FEM analysis of the magnetic flux density around the MMT showed that the magnetic flux density in the setup with the magnetic needles was around 8 times better than that in the setup without the needles. By magnetization, the drive frequency of the MMT improved by about 10 times-from 18 Hz to 180 Hz. We successfully demonstrated the separation of copolymer beads of a particular size in a chip by image sensing. © Springer Science+Business Media, LLC 2010.

**Author Keywords:** Lab-on-a-chip; Magnetically driven microtools; MEMS; Microactuator; Sorting

Year: 2010

Source title: Biomedical Microdevices

Volume: 12

Issue: 4

Page : 745-752

Cited by: 5

Link: [Scopus Link](#)

Document Type: Article

Source: Scopus

Authors with affiliations:

1. Yamanishi, Y., Japan Science and Technology Agency (JST), Department of Mechanical Science and Engineering, Nagoya University, Furo-cho, Chikusa-ku, Nagoya, 464-8603 Aichi-ken, Japan
2. Sakuma, S., Department of Bioengineering and Robotics, Tohoku University, 6-6-01, Aramaki-Aza-Aoba, Aoba-ku, Sendai, Miyagi-ken 980-8579, Japan

3. Onda, K., Department of Bioengineering and Robotics, Tohoku University, 6-6-01, Aramaki-Aza-Aoba, Aoba-ku, Sendai, Miyagi-ken 980-8579, Japan
4. Arai, F., Department of Mechanical Science and Engineering, Nagoya University, Furo-cho, Chikusa-ku, Nagoya, 464-8603 Aichi-ken, Japan